SAT Solving: Present and Future (in two vignettes)

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Logical Approaches to Barriers in Complexity II
From its head to its feet

In the last decade, SAT solving has become a tool used for many applications; see [BHvMW09] for an overview.

In my talk I want to discuss two problem areas

- which seem of importance to me for practical SAT solving,
- and where proof complexity should be able to offer solutions.

Sub-theme:

Tree-resolution has still a lot to offer, theoretically as well as practically.

Collaboration with my student Matthew Gwynne, and, recently started, with Olaf Beyersdorff.
1 Introduction

2 Hidden parameters
   - The general situation
   - Our approach

3 Good representations
   - The general situation
   - Our approach

4 Conclusions
Resolution parameters

We have three main resolution systems for SAT solving:

1. tree resolution
2. regular resolution
3. full (dag) resolution.

And there are three main parameters (with variations):

1. length
2. width
3. space

Finally there are two main types of complete SAT solvers:

- look-ahead (“DPLL”; close to tree resolution; effort on good branching and reduction)
- conflict-driven (“CDCL”; “approximates” dag resolution; effort on efficient learning).
Measuring “hardness”? 

It is tempting to use one of the resolution-parameters as a hidden parameter to measure the difficulty for SAT solving:

- A basic problem is that these measures are “nearly non-computable” (especially for instances of interest).
- And obviously a SAT solver doesn’t compute any of the measures — what degrees of “approximations” could be meaningful here?
What roles play the heuristics?

There are (important) heuristics for

- decision variable and decision value
- which clauses to learn
- which clauses to forget.

It is tempting to consider them as “approximating” resolution — what is the truth of this assumption?

A neglected aspect seems to me

1. complexity theory only performs asymptotical analysis
2. thus it can not be applied to any concrete instance.
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1. complexity theory only performs asymptotical analysis
2. thus it can not be applied to any concrete instance.

(((Big-Oh as the downfall of computer science.)))

Furthermore, SAT solvers also go beyond resolution
(at least in the polynomial factors)!
Towards a structural proof complexity theory

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Length and other measures are far too rough.
But proofs have “shapes”.

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I believe “shapes” can become better guides for SAT solvers than numbers.

- “Shape” should yield the general structure.
- Numbers are then for fine-tuning.
- These numbers need to have a heuristical reality.
Tree resolution is nice!

We have much better tools for tree-resolution than for dag-resolution:

- We have the “hardness”, which links basic SAT algorithms with length and space of tree resolution.
- Since “hardness” is algorithmic, we get quasi-automatisation of tree-resolution.
- The Pudlak-Impagliazzo game ([PI]) yields a game-theoretical interpretation of “hardness”.
- The Beyersdorff-Galesi games can yield precise(!) bounds for length.
- Last, but not least, we have a theory of branching heuristics ([Kul09]).
Reminder: Generalised UCP

Definition

The maps $r_k : \mathcal{CLS} \to \mathcal{CLS}$ for $k \in \mathbb{N}_0$ are defined as follows:

$$
\begin{align*}
    r_0(F) & := \begin{cases} 
    \{ \bot \} & \text{if } \bot \in F \\
    F & \text{otherwise}
    \end{cases} \\

    r_{k+1}(F) & := \begin{cases} 
    r_{k+1}(\langle x \to 1 \rangle \ast F) & \text{if } \exists x \in \text{lit}(F) : r_k(\langle x \to 0 \rangle \ast F) = \{ \bot \} \\
    F & \text{otherwise}
    \end{cases}
\end{align*}
$$

The map $r_\infty : \mathcal{CLS} \to \mathcal{CLS}$ is defined as $r_\infty(F) := r_{n(F)}(F)$.

Lemma

The maps are well-defined (don’t depend on the choices), and apply (only) forced assignments. The bigger $k$ the more forced assignments are found, and $r_\infty$ applies all forced assignments.
Reminder: “Hardness”

The $r_k$-reductions, allowing for oracles for SAT and UNSAT decisions (this will become important later), together with the notion of **hardness**, have been introduced in [Kul99, Kul04]:

**Definition**

The **hardness** $\text{hd}(F)$ of unsatisfiable $F$ is the minimal $k$ with $r_k(F) = \{\bot\}$.

1. $2^{\text{hd}(F)} \leq \text{Comp}_R^*(F) \leq (n(F) + 1)^{\text{hd}(F)}$.
2. $\text{hd}(F) + 1$ is the space complexity of tree-resolution.
3. $\text{hd}(F)$ is the level of nested input-resolution needed.
4. Considering the trivial oracle, the optimal value of the Pudlák-Impagliazzo game is equal to the hardness.
Practical applications

- $r_1$ is UCP (unit-clause propagation).
- $r_2$ is failed-literal reduction (full).
- Running $r_0, r_1, \ldots$ achieves quasi-automatisation of tree-resolution.
- Remark: In [Kul99, Kul04] there is also an algorithmic extension of hardness to satisfiable clause-sets, and so we have also “hardness” for finding satisfying assignments.
- This approach is also the kernel of the Stalmarck-approach (at CNF-level).
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That is, we are approaching **dag**-resolution.

- I haven’t seen yet any study at all, which would *show* (empirically) that it is “tree-like versus dag-like” what underlies the success of CDCL solvers.
- Though I accept it as a working hypothesis.

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However there is another working hypothesis:

If $\text{Comp}_R(F)$ and $\text{Comp}^*_R(F)$ are close,
then look-ahead solvers are (far) better.
Cube and Conquer

Based on [AKS11] (experiments in exact Ramsey theory)

- I “invented” a combination of look-ahead and conflict-driven SAT solvers
- which works on various classes far better than any solver alone
- and this also on classes where conflict-driven works far better than look-ahead.

In [HKWB12] this was implemented in a more “industrial” setting, and shown to yield very good results on SAT-competition benchmarks.
Best of both worlds: Combining Lookahead and CDCL
Dags only at the leaves

Another common assumption on CDCL-solvers is needed here:

- they are not good at finding large proofs
- they have a “point of competence”.

Then for instances which require dag-resolution, however not in an “entangled way”, we can split off the tree part, and let the CDCL-solvers work on the smaller problems.

1. So good instances are those which have good resolution refutations with a tree-like part at the root.

2. With Olaf Beyersdorff we started investigating “mixed proof systems”, based on [Kul99, Kul04], and now essentially employing the oracles at the leaves (using the CDCL solvers there).
Representing boolean functions

QBFs $F$ yield a natural framework for representations of boolean functions $f$ in the SAT context:

1. The free variables of $F$ are the variables of the boolean function $f$.
2. A satisfying assignment for $f$ is one making $F$ true.

Real practical applications has $\Sigma_1$-CNF, which I consider as most natural:

- A clause-set $F$ is a **CNF-representation** of the boolean function $f$ if $\text{var}(f) \subseteq \text{var}(F)$ and the satisfying assignments of $F$ projected to $\text{var}(f)$ are (precisely) the satisfying assignments of $f$.
- Important special case: $\text{var}(f) = \text{var}(F)$, i.e., *without using new variables* (so $F$ is equivalent to $f$).

We have $F \models f$, while in the other direction we need an extension.
“Good” representations

Translating a computational problem into a SAT-problem (should!) mean:

1. The building blocks are boolean functions (“constraints”) like “at most one” or cryptographic boxes.
2. For them “good” (currently this typically means short) representations are sought (possibly using new variables).
3. The whole translation is the union of these representations.

“Good” representation for SAT however does not mean “short”:

- It’s about how the solver can “handle” it.
- Experience with SAT-cryptanalysis of DES/AES suggests that for small boolean functions, actually shortest representations are best, however this changes for bigger boolean functions (there the small representations perform badly).

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Knowledge compilation?

The area of knowledge compilation (AI) has some relations to the theory of “good representations $F$ of a boolean function $f$”,

- since “all knowledge” about $f$ should be presented in $F$,
- and this in an “accessible form”,
- but the question is how the “retrieval” works!

“Good” SAT representations needs to be “understandable” by SAT solvers. This is rather different from knowledge compilation, where one has much more freedom in the retrieval mechanism.

And furthermore, although the prime implicates of prime implicants of $f$ are surely “prime knowledge” of $f$, that’s not all.
GAC and PC

The works in SAT being concerned about “good” representations borrowed the concept of “Generalised Arc Consistence” (GAC) from CP in the following way:

If after applying a partial assignment $\varphi$ to $f$ we obtain a forced assignment, then we obtain it from $\varphi \ast F$ via UCP.

This amounts to compression of the prime implicates of $f$ into $F$ via UCP.

What about the prime implicates of $F$ ?!

We argue that we need also the prime implicates of $F$. There is a related concept in the literature, namely “Propagation Completeness” (PC), being investigated rather recently and employed under different circumstances:

A clause-set $F$ is PC iff whenever $\varphi \ast F$ has a forced assignment, then we obtain it from $\varphi \ast F$ via UCP.
Good representations of $\text{PHP}_m^m$

Before making “good” more precise, let’s make things more concrete:

*Is there a “good representation” of $\text{PHP}_m^m$ (as boolean function)?*

Conjecture I  There is no good representation without using new variables.

Conjecture II  There is a good representation using new variables.
All conclusions must be “nicely” derivable

Our general framework for a “good” representation $F$ of $f$ is:

All conclusions $F \models C$ must be “easily derivable”.

Note that we consider all implication of $F$, not just those of $f$, since splitting on new variables is important.

So reasonable first measures are

- the binary logarithm of the maximum of resolution complexity of deriving $F \models C$,
- the binary logarithm of the maximum of tree-resolution complexity of deriving $F \models C$.

A “good representation” then has logarithmically bounded measures.
Hardness generalised

We propose a measurement with better properties:

- First mentioned in [ABLM08].
- For a clause-set $F$ the hardness is the maximum of $\text{hd}(\langle x \rightarrow 0 : x \in C \rangle \ast F)$ over $F \models C$.
- This is the maximum level of nested input resolution needed to derive all $F \models C$.

A “good” presentation is then one of bounded hardness.
Good representations

Our approach

Hardness — to be softened, not measured

[ABLM08] proposed “hardness” (for unsatisfiable clause-sets) as measure of solution hardness.

- Let’s call a clause-set $k$-soft if $\text{hd}(F) \leq k$.
- We think of the main role of hardness for satisfiable clause-sets as being a target, to construct soft clause-sets (representing relevant boolean functions).

Using [ČKV12] (where $k = 1$ is handled) we get:

**Lemma**

For $k \geq 1$ the decision $\text{hd}(F) \leq k$ is coNP-complete.

(Recall that for unsatisfiable $F$ computation of $\text{hd}(F)$ can be done in time $O(n^{2\text{hd}(F)})$.)
SLUR properly turned into a hierarchy

The class SLUR ([SAFS95, Fra97, FG03]) is equal to

\[ \{ F \in \mathcal{CLS} : \text{hd}(F) \leq 1 \} . \]

Using “\( \text{hd}(F) \leq k \)” we obtain a natural hierarchy.
Propagation-hardness

Now we have handled GAC properly. What about PC?

Definition

The propagation-hardness ("p-hardness") \( \text{phd}(F) \) of \( F \in \mathcal{CLS} \) is the minimal \( k \geq 1 \) such that for all partial assignments \( \varphi \) we have

\[
 r_k(\varphi \ast F) = r_{\infty}(\varphi \ast F).
\]

The class PC is equal to

\[
 \{ F \in \mathcal{CLS} : \text{phd}(F) \leq 1 \}.
\]

Using "\( \text{phd}(F) \leq k \)" we obtain again a natural hierarchy (strengthening the SLUR-hierarchy).
Proper representation-hierarchies

We can show that going from $k$ to $k + 1$ enables exponentially shorter representations (with that given (p-)hardness), when not using new variables.

It seems quite hard to show such a result when allowing new variables.
Now we have various possibilities to make the two conjectures precise:

Your turn!

Just to mention: For arbitrary \( m, n \) we have

\[
\text{hd}(\text{PHP}^m_n) = \min(\max(m - 1, 0), n).
\]

(The task is now to consider arbitrary representations of \( \text{PHP}^m_n \).)
Consider SAT!

As we have seen, satisfiable clause-set $F$ become in this way an object of proof theory:

It’s about the unsatisfiable clause-sets obtained by applying partial assignments to $F$.

And a major perspective change is needed:

Not given $F$ are to be studied, but all $F$ representing a given boolean function.
Conclusions

Understanding hardness of SAT solving:
- Study shape, not just numbers!
- Cube and Conquer is based on a two-phase proof search, combing tree- and dag-resolution.

Understanding SAT translations:
- Hardness and p-hardness as general measures of goodness of representations.
- New proof theory of SAT (taken literally).


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