

# Distributional proving problems, and beyond

Edward A. Hirsch

(based on results of  
E.A.H., D. Itsykson, I. Monakhov, V. Nikolaenko, A. Smal, D. Sokolov)

Steklov Institute of Mathematics at St.Petersburg, RAS  
St.Petersburg Academic University, RAS

# Distributional proving problems

Distributional proving problem  $(D, L)$  consists of

- ▶ a language  $L$  of “theorems”,
- ▶ a polynomial-time samplable distribution  $D = \{D_n\}_{n \in \mathbb{N}}$  on  $\bar{L}$ .

Motivation:

- ▶ a small (wrt  $D$ ) amount of wrong theorems is acceptable;
- ▶ not interested in what happens on statements that are not claimed;
- ▶ polynomial-time samplable distributions are concentrated on **NP** languages, thus the definition is natural for  $L \in \mathbf{co-NP}$ .

## Heuristic proof systems

- ▶ Allow probabilistic proof verification (with bounded error).
- ▶ Allow small number of false theorems (unbounded error there) according to  $D$ .
- ▶ Heuristic computation: gets  $d$  on input and makes at most  $\frac{1}{d}$  errors.

# Heuristic proof systems

- ▶ Allow probabilistic proof verification (with bounded error).
- ▶ Allow small number of false theorems (unbounded error there) according to  $D$ .
- ▶ Heuristic computation: gets  $d$  on input and makes at most  $\frac{1}{d}$  errors.

## Definition

**Heuristic proof system** for  $(D, L)$  is a polynomial-time  $\Pi$  such that

(completeness) There is a proof accepted whp

(correctness) Most non-theorems don't have such proofs:

# Heuristic proof systems

- ▶ Allow probabilistic proof verification (with bounded error).
- ▶ Allow small number of false theorems (unbounded error there) according to  $D$ .
- ▶ Heuristic computation: gets  $d$  on input and makes at most  $\frac{1}{d}$  errors.

## Definition

**Heuristic proof system** for  $(D, L)$  is a polynomial-time  $\Pi$  such that

(completeness) There is a proof accepted whp:

$$\forall x \in L \forall d \in \mathbb{N} \exists w \quad \Pr\{\Pi(x, w, d) = 1\} > \frac{1}{2}.$$

(Such  $w$  is a  $\Pi$ -proof with confidence  $d$ .)

(correctness) Most non-theorems don't have such proofs:

$$\Pr_{r \leftarrow D_n} \{\exists w \{\Pr\{\Pi(r, w, d) = 1\} > \frac{1}{8}\}\} < \frac{1}{d}.$$

## Turning AM protocols into heuristic proof systems

- ▶ Assume  $L \in \mathbf{AM}$ .  
(E.g.,  $L = \text{GNI}$ ,  $D$  samples random isomorphic graphs.)
- ▶ Consider a protocol  $(A, M)$  for  $L$   
(w.l.o.g., with perfect completeness and exponentially small error):

$$x \in L \implies \forall r \exists w A(x, w, r) = 1,$$

$$x \notin L \implies \Pr_r \{ \exists w A(x, w, r) = 1 \} < 2^{-|x|}.$$

## Turning AM protocols into heuristic proof systems

- ▶ Assume  $L \in \mathbf{AM}$ .  
(E.g.,  $L = \text{GNI}$ ,  $D$  samples random isomorphic graphs.)
- ▶ Consider a protocol  $(A, M)$  for  $L$   
(w.l.o.g., with perfect completeness and exponentially small error):

$$x \in L \implies \forall r \exists w A(x, w, r) = 1,$$

$$x \notin L \implies \Pr_r \{ \exists w A(x, w, r) = 1 \} < 2^{-|x|}.$$

- ▶ Consider  $L' = \{(x, r) \mid x \in L\}$ , where the length of  $r$  is enough to make the public random choices.
- ▶ Consider  $D' = D \times U$ , where  $D$  is any “original” distribution on  $\bar{L}$  and  $U$  is the uniform distribution.

# Turning AM protocols into heuristic proof systems

- ▶ Assume  $L \in \mathbf{AM}$ .  
(E.g.,  $L = \text{GNI}$ ,  $D$  samples random isomorphic graphs.)
- ▶ Consider a protocol  $(A, M)$  for  $L$   
(w.l.o.g., with perfect completeness and exponentially small error):

$$x \in L \implies \forall r \exists w A(x, w, r) = 1,$$

$$x \notin L \implies \Pr_r \{ \exists w A(x, w, r) = 1 \} < 2^{-|x|}.$$

- ▶ Consider  $L' = \{(x, r) \mid x \in L\}$ , where the length of  $r$  is enough to make the public random choices.
- ▶ Consider  $D' = D \times U$ , where  $D$  is any “original” distribution on  $\bar{L}$  and  $U$  is the uniform distribution.

## Theorem (Itsykson, Sokolov)

- (1)  $(L', D')$  has a polynomially bounded heuristic p.s.
- (2) if  $L' \in \mathbf{NP}$ , then  $L \in \mathbf{NP}$ .

- ▶ Proof: Simulate  $A$  using  $r$ .



# Turning AM protocols into heuristic proof systems

## Discussion

**Question:** **AM** protocols make **deterministic** (heuristic) proof systems with **very small error**. Suggest another example: make use of randomness and larger error (dependent on the running time), go outside **AM**.

# Turning AM protocols into heuristic proof systems

## Discussion

**Question:** AM protocols make **deterministic** (heuristic) proof systems with **very small error**. Suggest another example: make use of randomness and larger error (dependent on the running time), go outside **AM**.

- ▶ Consider  $L' = \{(x, r) \mid x \in L\}$ , where the length of  $r$  is enough to make the public random choices.
- ▶ Consider  $D' = D \times U$ , where  $D$  is any “original” distribution on  $\bar{L}$  and  $U$  is the uniform distribution.

**Question:** Is there a heuristic algorithm for  $(L', D')$ ?

**Answer:**

# Turning AM protocols into heuristic proof systems

## Discussion

**Question:** AM protocols make **deterministic** (heuristic) proof systems with **very small error**. Suggest another example: make use of randomness and larger error (dependent on the running time), go outside **AM**.

- ▶ Consider  $L' = \{(x, r) \mid x \in L\}$ , where the length of  $r$  is enough to make the public random choices.
- ▶ Consider  $D' = D \times U$ , where  $D$  is any “original” distribution on  $\bar{L}$  and  $U$  is the uniform distribution.

**Question:** Is there a heuristic algorithm for  $(L', D')$ ?

**Answer:** We don't know.

# Turning AM protocols into heuristic proof systems

## Discussion

**Question:** AM protocols make **deterministic** (heuristic) proof systems with **very small error**. Suggest another example: make use of randomness and larger error (dependent on the running time), go outside **AM**.

- ▶ Consider  $L' = \{(x, r) \mid x \in L\}$ , where the length of  $r$  is enough to make the public random choices.
- ▶ Consider  $D' = D \times U$ , where  $D$  is any “original” distribution on  $\bar{L}$  and  $U$  is the uniform distribution.

**Question:** Is there a heuristic algorithm for  $(L', D')$ ?

**Answer:** ~~We don't know.~~

Implies randomized heuristic algorithm for  $(L, D)$ .

# Heuristic acceptors

## Definition

(Classical) acceptor  $A$  for  $L$ :

(completeness)  $A$  accepts every  $x \in L$ .

(correctness)  $A$  does not stop on any  $x \notin L$ .

# Heuristic acceptors

**Distributional proving problem**  $(D, L)$  consists of a language  $L$  of “theorems” and a polynomial-time samplable distribution  $D = \{D_n\}_{n \in \mathbb{N}}$  on  $\bar{L}$ .

## Definition

Heuristic acceptor  $A$  for  $(D, L)$ :

(completeness)  $\forall x \in L \forall d \in \mathbb{N} \quad A(x, d) = 1.$

(correctness)  $\Pr_{r \leftarrow D_n} \{ \Pr_A \{ A(r, d) = 1 \} > \frac{1}{8} \} < \frac{1}{d}.$

(correctness')  $\Pr_{r \leftarrow D_n; A} \{ A(r, d) = 1 \} < \frac{1}{d}.$

# Heuristic acceptors

**Distributional proving problem**  $(D, L)$  consists of a language  $L$  of “theorems” and a polynomial-time samplable distribution  $D = \{D_n\}_{n \in \mathbb{N}}$  on  $\bar{L}$ .

## Definition

Heuristic acceptor  $A$  for  $(D, L)$ :

(completeness)  $\forall x \in L \forall d \in \mathbb{N} \quad A(x, d) = 1$ .

(correctness)  $\Pr_{r \leftarrow D_n} \{ \Pr_A \{ A(r, d) = 1 \} > \frac{1}{8} \} < \frac{1}{d}$ .

(correctness')  $\Pr_{r \leftarrow D_n; A} \{ A(r, d) = 1 \} < \frac{1}{d}$ .

- ▶ Time  $\tau_A(x, d)$  is a **random variable**.
- ▶ For random variable  $X$ , define  $\mu^{(p)}[X] = \min\{T : \Pr[X \geq T] \geq p\}$ .
- ▶  $t_A(x) = \mu^{(1/2)}[\tau_A(x, d)]$  is the median running time of  $A(x, d)$ .

# Heuristic acceptors

**Distributional proving problem**  $(D, L)$  consists of a language  $L$  of “theorems” and a polynomial-time samplable distribution  $D = \{D_n\}_{n \in \mathbb{N}}$  on  $\bar{L}$ .

## Definition

Heuristic acceptor  $A$  for  $(D, L)$ :

(completeness)  $\forall x \in L \forall d \in \mathbb{N} \quad A(x, d) = 1.$

(correctness)  $\Pr_{r \leftarrow D_n} \{ \Pr_A \{ A(r, d) = 1 \} > \frac{1}{8} \} < \frac{1}{d}.$

(correctness')  $\Pr_{r \leftarrow D_n; A} \{ A(r, d) = 1 \} < \frac{1}{d}.$

- ▶ Time  $\tau_A(x, d)$  is a **random variable**.
- ▶ For random variable  $X$ , define  $\mu^{(p)}[X] = \min\{T : \Pr[X \geq T] \geq p\}.$
- ▶  $t_A(x) = \mu^{(1/2)}[\tau_A(x, d)]$  is the median running time of  $A(x, d).$

## Theorem

$\exists$  polynomial-time samplable  $D \exists L \in \mathbf{co-NP} \nexists$  polynomial-time heuristic acceptor for  $(D, L) \iff \exists$  infinitely-often one-way function.



# Optimal heuristic acceptor

## Definition

(Classical) acceptor  $S$  **simulates**  $W$  if there is a polynomial  $p$  such that  $\forall x \in L, \quad t_S(x) \leq p(t_W(x) \cdot |x|)$ .

# Optimal heuristic acceptor

## Definition

Heuristic acceptor  $S$  **simulates**  $W$  if there are polynomials  $p$  and  $q$  such that  $\forall x \in L, \forall d \in \mathbb{N}, \quad t_S(x, d) \leq \max_{d' \leq q(d \cdot |x|)} p(t_W(x, d')) \cdot |x| \cdot d$ .

**Idea:** Certify  $A_i$  by testing it on samples  $x \leftarrow D_n$ .

# Optimal heuristic acceptor

## Definition

Heuristic acceptor  $S$  **simulates**  $W$  if there are polynomials  $p$  and  $q$  such that  $\forall x \in L, \forall d \in \mathbb{N}, \quad t_S(x, d) \leq \max_{d' \leq q(d \cdot |x|)} p(t_W(x, d')) \cdot |x| \cdot d$ .

**Idea:** Certify  $A_i$  by testing it on samples  $x \leftarrow D_n$ .

Optimal heuristic acceptor  $U(x, d)$ :

- ▶ For each  $i \leq \log |x|$  in parallel:
  1. Execute  $A_i(x, d')$ .

## Definition

Heuristic acceptor  $S$  **simulates**  $W$  if there are polynomials  $p$  and  $q$  such that  $\forall x \in L, \forall d \in \mathbb{N}$ ,

$$t_S(x, d) \leq \max_{d' \leq q(d \cdot |x|)} p(t_W(x, d')) \cdot |x| \cdot d.$$

**Idea:** Certify  $A_i$  by testing it on samples  $x \leftarrow D_n$ .

Optimal heuristic acceptor  $U(x, d)$ :

- ▶ For each  $i \leq \log |x|$  in parallel:
  1. Execute  $A_i(x, d')$ .
  2. If it accepts (in  $T_i$  steps), test its correctness:  
let  $E_i = 0$  and execute  $k$  times:
    - ▶  $r \leftarrow D_{|x|}$ ,
    - ▶ if  $A_i(r, d') = 1$  in  $T_i$  steps, then  $E_i := E_i + 1$ ;

# Optimal heuristic acceptor

## Definition

Heuristic acceptor  $S$  **simulates**  $W$  if there are polynomials  $p$  and  $q$  such that  $\forall x \in L, \forall d \in \mathbb{N}$ ,

$$t_S(x, d) \leq \max_{d' \leq q(d \cdot |x|)} p(t_W(x, d')) \cdot |x| \cdot d.$$

**Idea:** Certify  $A_i$  by testing it on samples  $x \leftarrow D_n$ .

Optimal heuristic acceptor  $U(x, d)$ :

- ▶ For each  $i \leq \log |x|$  in parallel:
  1. Execute  $A_i(x, d')$ .
  2. If it accepts (in  $T_i$  steps), test its correctness:  
let  $E_i = 0$  and execute  $k$  times:
    - ▶  $r \leftarrow D_{|x|}$ ,
    - ▶ if  $A_i(r, d') = 1$  in  $T_i$  steps, then  $E_i := E_i + 1$ ;
  3. If  $E_i < \delta k$ , output “1”.

# Optimal heuristic acceptor

## Definition

Heuristic acceptor  $S$  **simulates**  $W$  if there are polynomials  $p$  and  $q$  such that  $\forall x \in L, \forall d \in \mathbb{N}$ ,

$$t_S(x, d) \leq \max_{d' \leq q(d \cdot |x|)} p(t_W(x, d')) \cdot |x| \cdot d.$$

**Idea:** Certify  $A_i$  by testing it on samples  $x \leftarrow D_n$ .

Optimal heuristic acceptor  $U(x, d)$ :

- ▶ For each  $i \leq \log |x|$  in parallel:
  1. Execute  $A_i(x, d')$ .
  2. If it accepts (in  $T_i$  steps), test its correctness:  
let  $E_i = 0$  and execute  $k$  times:
    - ▶  $r \leftarrow D_{|x|}$ ,
    - ▶ if  $A_i(r, d') = 1$  in  $T_i$  steps, then  $E_i := E_i + 1$ ;
  3. If  $E_i < \delta k$ , output “1”.

Here  $d' = 4d|x|$ ,  $k = 2d^3|x|^3$ ,  $\delta = \frac{1}{2d|x|}$ .

## Optimal proof systems

- ▶ A proof system  $\Sigma$  **simulates** a proof system  $\Omega$  iff  $\Sigma$ -proofs are at most as long as  $\Omega$ -proofs (up to a polynomial  $p$ ):

$$\forall F \in L \quad |\text{shortest } \Sigma\text{-proof of } F| \leq p(|\text{shortest } \Omega\text{-proof of } F|, |F|).$$

- ▶  **$p$ -simulation** is a constructive version: For any  $w$ -size  $\Omega$ -proof, one can compute a  $p(w)$ -size  $\Sigma$ -proof in polynomial time.
- ▶  **$(p)$ -optimal** proof system  $(p)$ -simulates any other proof system.
- ▶ **Does it exist?..**

# Optimal proof systems

- ▶ A proof system  $\Sigma$  **simulates** a proof system  $\Omega$  iff  $\Sigma$ -proofs are at most as long as  $\Omega$ -proofs (up to a polynomial  $p$ ):  
$$\forall F \in L \quad |\text{shortest } \Sigma\text{-proof of } F| \leq p(|\text{shortest } \Omega\text{-proof of } F|, |F|).$$
- ▶  **$p$ -simulation** is a constructive version: For any  $w$ -size  $\Omega$ -proof, one can compute a  $p(w)$ -size  $\Sigma$ -proof in polynomial time.
- ▶  **$(p)$ -optimal** proof system  $(p)$ -simulates any other proof system.
- ▶ **Does it exist?..**

## Theorem

$\exists$   **$p$ -optimal proof system**  $\iff \exists$  **optimal acceptor**.

For **TAUT**: [Krajíček, Pudlák].

For paddable languages: [Messner].

For **co-NP**-complete languages: [Chen, Flüm, Müller].



# Simulations

▶ **pointwise** simulation  $\mathcal{A} \prec \mathcal{B}$ :

$\exists$  polynomial  $p \forall x$

$$t_{\mathcal{A}}(x) \leq p(t_{\mathcal{B}}(x) + |x|)$$

# Simulations

- ▶ **pointwise** simulation  $\mathcal{A} \prec \mathcal{B}$ :

$\exists$  polynomial  $p \forall x$

$$t_{\mathcal{A}}(x) \leq p(t_{\mathcal{B}}(x) + |x|)$$

- ▶ (yet weaker!) **worst-case** simulation  $\mathcal{A} \prec_{wc} \mathcal{B}$ :

$\exists$  polynomials  $p, q \forall x$

$$t_{\mathcal{A}}(x) \leq p\left(\max_{\substack{|x'| \leq q(|x|) \\ x' \in L}} t_{\mathcal{B}}(x') + |x|\right)$$

# Simulations

- ▶ **pointwise** simulation  $\mathcal{A} \prec \mathcal{B}$ :

$\exists$  polynomial  $p \forall x$

$$t_{\mathcal{A}}(x) \leq p(t_{\mathcal{B}}(x) + |x|)$$

- ▶ (weaker) **average-case** simulation  $\mathcal{A} \prec_D \mathcal{B}$  w.r.t.  $D$ :

$\forall \epsilon > 0 \exists c > 0$

$$\mathbf{E}_{x \leftarrow D_n} [t_{\mathcal{A}}^c(x)] = O(n \mathbf{E}_{y \leftarrow D_n} [t_{\mathcal{B}}^\epsilon(y)])$$

- ▶ (yet weaker!) **worst-case** simulation  $\mathcal{A} \prec_{wc} \mathcal{B}$ :

$\exists$  polynomials  $p, q \forall x$

$$t_{\mathcal{A}}(x) \leq p\left(\max_{\substack{|x'| \leq q(|x|) \\ x' \in L}} t_{\mathcal{B}}(x') + |x|\right)$$

# Simulations

- ▶ **pointwise** simulation  $\mathcal{A} \prec \mathcal{B}$ :

$\exists$  polynomial  $p \forall x$

$$t_{\mathcal{A}}(x) \leq p(t_{\mathcal{B}}(x) + |x|)$$

- ▶ (weaker) **average-case** simulation  $\mathcal{A} \prec_D \mathcal{B}$  w.r.t.  $D$ :

$\forall \epsilon > 0 \exists c > 0$

$$\mathbf{E}_{x \leftarrow D_n} [t_{\mathcal{A}}^c(x)] = O(n \mathbf{E}_{y \leftarrow D_n} [t_{\mathcal{B}}^\epsilon(y)])$$

- ▶ (weaker) simulation **scheme**:

simulate everywhere except for the set of  $D$ -prob.  $1/2d$ .

- ▶ (yet weaker!) **worst-case** simulation  $\mathcal{A} \prec_{wc} \mathcal{B}$ :

$\exists$  polynomials  $p, q \forall x$

$$t_{\mathcal{A}}(x) \leq p\left(\max_{\substack{|x'| \leq q(|x|) \\ x' \in L}} t_{\mathcal{B}}(x') + |x|\right)$$

## Problems and complexities

- ▶ **Decision** problem  $L$ : is  $x \in L$ ?  
Solved by **decision algorithms**: complexity measure = time.

## Problems and complexities

- ▶ **Decision** problem  $L$ : is  $x \in L$ ?  
Solved by **decision algorithms**: complexity measure = time.
- ▶ Same problem, solved by **acceptors**: complexity measure = time on  $L$ .

# Problems and complexities

- ▶ **Decision** problem  $L$ : is  $x \in L$ ?  
Solved by **decision algorithms**: complexity measure = time.
- ▶ Same problem, solved by **acceptors**: complexity measure = time on  $L$ .
  - ▶ **worst-case optimal acceptor for NP-complete problems:**  
**Levin's universal search + self-to-decision reduction:**  
On input  $x$ , run  $|x|$  algorithms in parallel:
    1.  $A_1(x)$  (brute-force search); output the result;
    2.  $A_2(x)$ ; check the solution; output if it's correct;
    - ...
    - $n$ .  $A_{|x|}(x)$ ; check the solution; output if it's correct.

# Problems and complexities

- ▶ **Decision** problem  $L$ : is  $x \in L$ ?  
Solved by **decision algorithms**: complexity measure = time.
- ▶ Same problem, solved by **acceptors**: complexity measure = time on  $L$ .
  - ▶ **worst-case optimal acceptor for NP-complete problems:**  
**Levin's universal search + self-to-decision reduction:**  
On input  $x$ , run  $|x|$  algorithms in parallel:
    1.  $A_1(x)$  (brute-force search); output the result;
    2.  $A_2(x)$ ; check the solution; output if it's correct;
    - ...
    - $n$ .  $A_{|x|}(x)$ ; check the solution; output if it's correct.

**Not** a pointwise optimal acceptor for **co-NP** problems;

**Not** a pointwise optimal acceptor for **NP** problems;

**Main obstacle:** how to verify a 1-bit answer to a decision problem?

Worst-case optimal acceptor for **NP**-complete problems:

extract satisfying assignment for  $F$  by queries to  $F[v = 0]$ ,  $F[v = 1]$



# Problems and complexities

- ▶ **Decision** problem  $L$ : is  $x \in L$ ?  
Solved by **decision algorithms**: complexity measure = time.
- ▶ Same problem, solved by **acceptors**: complexity measure = time on  $L$ .
  - ▶ worst-case optimal acceptor for **NP**-complete problems:  
Levin's universal search + self-to-decision reduction.
  - ▶ worst-case (and stronger) optimal randomized acceptor for GNI:  
verification by Goldwasser-Micali-Sipser protocol.

# Problems and complexities

- ▶ **Decision** problem  $L$ : is  $x \in L$ ?  
Solved by **decision algorithms**: complexity measure = time.
- ▶ Same problem, solved by **acceptors**: complexity measure = time on  $L$ .
  - ▶ worst-case optimal acceptor for **NP**-complete problems:  
Levin's universal search + self-to-decision reduction.
  - ▶ worst-case (and stronger) optimal randomized acceptor for GNI.
  - ▶ pointwise-optimal acceptor for Time( $f$ )-immune sets [Messner],  
pointwise-optimal algorithm for bi-immune sets [Chen, Flum, Müller].

# Problems and complexities

- ▶ **Decision** problem  $L$ : is  $x \in L$ ?  
Solved by **decision algorithms**: complexity measure = time.
- ▶ Same problem, solved by **acceptors**: complexity measure = time on  $L$ .
  - ▶ worst-case optimal acceptor for **NP**-complete problems:  
Levin's universal search + self-to-decision reduction.
  - ▶ worst-case (and stronger) optimal randomized acceptor for GNI.
  - ▶ pointwise-optimal acceptor, algorithm for a set in  $\mathbf{E} \setminus \mathbf{P}$ .
- ▶ **Distributional** problem  $(D, L)$ : is  $x \in L$  with accuracy  $d$ ?  
Complexity measure =  $\text{time}(n, d)$ .  
Errorless average-case complexity: count  $\mathbf{E}$  or give up with  $D$ -prob.  $1/d$ .
  - ▶ average-case optimal randomized acceptor for GNI for some  $D$ .

# Problems and complexities

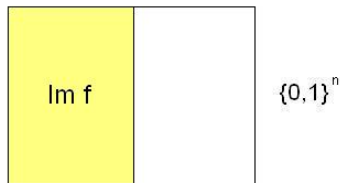
- ▶ **Decision** problem  $L$ : is  $x \in L$ ?  
Solved by **decision algorithms**: complexity measure = time.
- ▶ Same problem, solved by **acceptors**: complexity measure = time on  $L$ .
  - ▶ worst-case optimal acceptor for **NP**-complete problems:  
Levin's universal search + self-to-decision reduction.
  - ▶ worst-case (and stronger) optimal randomized acceptor for GNI.
  - ▶ pointwise-optimal acceptor, algorithm for a set in  $\mathbf{E} \setminus \mathbf{P}$ .
- ▶ **Distributional** problem  $(D, L)$ : is  $x \in L$  with accuracy  $d$ ?  
Complexity measure =  $\text{time}(n, d)$ .  
Errorless average-case complexity: count  $\mathbf{E}$  or give up with  $D$ -prob.  $1/d$ .
  - ▶ average-case optimal randomized acceptor for GNI for some  $D$ .
- ▶ Same problem, solved by **heuristic algorithms**:  
allow false negatives and positives with  $D$ -prob.  $1/d$ .
  - ▶ pointwise optimal randomized *algorithm* for  $\mathbf{Im}$  of an injective function,
  - ▶ "scheme-optimal" deterministic *algorithm* for "—" "—" "—".

# Problems and complexities

- ▶ **Decision** problem  $L$ : is  $x \in L$ ?  
Solved by **decision algorithms**: complexity measure = time.
- ▶ Same problem, solved by **acceptors**: complexity measure = time on  $L$ .
  - ▶ worst-case optimal acceptor for **NP**-complete problems:  
Levin's universal search + self-to-decision reduction.
  - ▶ worst-case (and stronger) optimal randomized acceptor for GNI.
  - ▶ pointwise-optimal acceptor, algorithm for a set in  $\mathbf{E} \setminus \mathbf{P}$ .
- ▶ **Distributional** problem  $(D, L)$ : is  $x \in L$  with accuracy  $d$ ?  
Complexity measure =  $\text{time}(n, d)$ .  
Errorless average-case complexity: count  $\mathbf{E}$  or give up with  $D$ -prob.  $1/d$ .
  - ▶ average-case optimal randomized acceptor for GNI for some  $D$ .
- ▶ Same problem, solved by **heuristic algorithms**:  
allow false negatives and positives with  $D$ -prob.  $1/d$ .
  - ▶ pointwise optimal randomized *algorithm* for  $\mathbf{Im}$  of an injective function,
  - ▶ "scheme-optimal" deterministic *algorithm* for  $- - -$ .
- ▶ **Distributional proving** problem  $(D, L)$ :  $\text{supp } D \subseteq \bar{L}$ .  
Solved by heuristic acceptors, may allow false positives only.
  - ▶ pointwise optimal randomized heuristic acceptor for p.-t.s.  $D$ , r.e.  $L$

# Derandomization

Deterministic *scheme*-optimal acceptor for  $(U, \overline{\text{Im } f})$ , where...



- ▶  $f : \{0, 1\}^* \rightarrow \{0, 1\}^*$ ,
- ▶  $|f(x)| = |x| + 1$ ,
- ▶  $f$  is injective,
- ▶  $f$  is polynomial-time computable.

## Derandomization

Deterministic *scheme*-optimal acceptor for  $(U, \overline{\text{Im } f})$ ,

- ▶ Use pseudorandom graph based on expanders.
- ▶ The input is a source of randomness!

# Derandomization

Deterministic *scheme*-optimal acceptor for  $(U, \overline{\text{Im } f})$ ,

- ▶ Use pseudorandom graph based on expanders.
- ▶ The input is a source of randomness!
- ▶ Not optimal when the simulated algorithm is erroneously disqualified.

## Definition

Simulation **scheme** of  $A$  by  $A'$ :

Simulate everywhere except for the fraction  $\frac{1}{2d}$ :

$\exists$  polynomials  $p, q \forall n, d \in \mathbb{N}$

$$\Pr_{x \leftarrow D_n} [t_A(x, d) \leq p(n \cdot d \cdot t_{A'}(x, q(n, d)))] \geq 1 - \frac{1}{2d},$$

$$q(n, d) \geq 2d.$$



# Graph nonisomorphism

$$\text{GNI} = \{(G_1, G_2) \mid G_1 \not\cong G_2, |V(G_1)| = |V(G_2)|\},$$

- ▶  $n$  is the number of vertices,
- ▶  $G^\pi$  is the result of permuting  $V(G)$  by  $\pi \in S_n$ .

# Graph nonisomorphism

$\text{GNI} = \{(G_1, G_2) \mid G_1 \not\cong G_2, |V(G_1)| = |V(G_2)|\}$ ,

- ▶  $n$  is the number of vertices,
- ▶  $G^\pi$  is the result of permuting  $V(G)$  by  $\pi \in S_n$ .

Recall **two-round interactive protocol** for GNI

[Goldreich, Micali, Wigderson, 1987]:

- ▶ Prover claims that  $G_1 \not\cong G_2$ ;
- ▶ Verifier picks random  $i \in \{1, 2\}$ ,  $\pi \in S_n$  and sends  $G_i^\pi$ ;
- ▶ Prover sends  $j$ ;
- ▶ Verifier accepts if  $i = j$ .

# Graph nonisomorphism

$\text{GNI} = \{(G_1, G_2) \mid G_1 \not\cong G_2, |V(G_1)| = |V(G_2)|\}$ ,

- ▶  $n$  is the number of vertices,
- ▶  $G^\pi$  is the result of permuting  $V(G)$  by  $\pi \in S_n$ .

Recall **two-round interactive protocol** for GNI

[Goldreich, Micali, Wigderson, 1987]:

- ▶ Prover claims that  $G_1 \not\cong G_2$ ;
- ▶ Verifier picks random  $i \in \{1, 2\}$ ,  $\pi \in S_n$  and sends  $G_i^\pi$ ;
- ▶ Prover sends  $j$ ;
- ▶ Verifier accepts if  $i = j$ .

If the claim is wrong, Verifier rejects with probability  $\geq 1/2$ .

# Correcting a GNI algorithm

$\text{SelfCorrect}_{A,N}$ , corrects any (randomized) algorithm  $A$ :

- ▶ Run  $N + 1$  instances of  $A$  in parallel for random  $\pi_{ij} \in S_n$ :
  - ▶  $A(G_1^{\pi_{11}}, G_1^{\pi_{12}})$
  - ▶  $A(G_1^{\pi_{21}}, G_1^{\pi_{22}})$
  - ▶ ...
  - ▶  $A(G_1^{\pi_{N1}}, G_1^{\pi_{N2}})$
  - ▶  $A(G_1^{\pi_{N+1,1}}, G_2^{\pi_{N+1,2}})$
- ▶ Return 1 if the last instance was the fastest; otherwise diverge.

# Correcting a GNI algorithm

$\text{SelfCorrect}_{A,N}$ , corrects any (randomized) algorithm  $A$ :

- ▶ Run  $N + 1$  instances of  $A$  in parallel for random  $\pi_{ij} \in S_n$ :
  - ▶  $A(G_1^{\pi_{11}}, G_1^{\pi_{12}})$
  - ▶  $A(G_1^{\pi_{21}}, G_1^{\pi_{22}})$
  - ▶ ...
  - ▶  $A(G_1^{\pi_{N1}}, G_1^{\pi_{N2}})$
  - ▶  $A(G_1^{\pi_{N+1,1}}, G_2^{\pi_{N+1,2}})$
- ▶ Return 1 if the last instance was the fastest; otherwise diverge.

## Lemma

- ▶ If  $G_1 \simeq G_2$ , then  $\Pr[\text{accept}] \leq \frac{1}{N+1}$ .
- ▶ If  $G_1 \not\approx G_2$  and  $A$  errs with probability  $\leq \frac{1}{2^n}$ , then  $\Pr[\text{accept}] \geq 1 - \frac{N+1}{2^n}$ .

## Optimal acceptor for GNI

Algorithm  $Opt(G_1, G_2)$ :

- ▶ Execute in parallel:
  - ▶  $A_1(G_1, G_2)$  (brute-force search),
  - ▶ 3 times  $SelfCorrect_{A_2, 30n}(G_1, G_2)$ ,
  - ▶ 3 times  $SelfCorrect_{A_3, 30n}(G_1, G_2)$ ,
  - ▶ ...
  - ▶ 3 times  $SelfCorrect_{A_n, 30n}(G_1, G_2)$ .
- ▶ Accept if any of the  $3n + 1$  parallel threads accepts.

# Optimal acceptor for GNI

Algorithm  $Opt(G_1, G_2)$ :

- ▶ Execute in parallel:
  - ▶  $A_1(G_1, G_2)$  (brute-force search),
  - ▶ 3 times  $SelfCorrect_{A_2, 30n}(G_1, G_2)$ ,
  - ▶ 3 times  $SelfCorrect_{A_3, 30n}(G_1, G_2)$ ,
  - ▶ ...
  - ▶ 3 times  $SelfCorrect_{A_n, 30n}(G_1, G_2)$ .
- ▶ Accept if any of the  $3n + 1$  parallel threads accepts.

Lemma (correctness)

If  $G_1 \simeq G_2$ , then  $\Pr[Opt(G_1, G_2) = 1] \leq \frac{3n}{30n+1} < \frac{1}{10}$ .

# Optimal acceptor for GNI

Algorithm  $Opt(G_1, G_2)$ :

- ▶ Execute in parallel:
  - ▶  $A_1(G_1, G_2)$  (brute-force search),
  - ▶ 3 times  $SelfCorrect_{A_2, 30n}(G_1, G_2)$ ,
  - ▶ 3 times  $SelfCorrect_{A_3, 30n}(G_1, G_2)$ ,
  - ▶ ...
  - ▶ 3 times  $SelfCorrect_{A_n, 30n}(G_1, G_2)$ .
- ▶ Accept if any of the  $3n + 1$  parallel threads accepts.

## Lemma (correctness)

If  $G_1 \simeq G_2$ , then  $\Pr[Opt(G_1, G_2) = 1] \leq \frac{3n}{30n+1} < \frac{1}{10}$ .

## Lemma (simulation)

For any randomized acceptor  $A$  for GNI  $\exists$  polynomial  $p$  such that

$\forall x \in GNI, t_{Opt}(x) \leq p\left(\mu_{y \leftarrow U(C_x)}[\tau_A(y)]\right)$ , where

$C_{(G_1, G_2)} = \{(G_1^{\pi_1}, G_2^{\pi_2}) \mid \pi_1, \pi_2 \in S_n\}$  is a *cluster* of  $(G_1, G_2)$ .



# Optimal acceptor for GNI

Algorithm  $Opt(G_1, G_2)$ :

- ▶ Execute in parallel:
  - ▶  $A_1(G_1, G_2)$  (brute-force search),
  - ▶ 3 times  $SelfCorrect_{A_2, 30n}(G_1, G_2)$ ,
  - ▶ 3 times  $SelfCorrect_{A_3, 30n}(G_1, G_2)$ ,
  - ▶ ...
  - ▶ 3 times  $SelfCorrect_{A_n, 30n}(G_1, G_2)$ .
- ▶ Accept if any of the  $3n + 1$  parallel threads accepts.

## Lemma (simulation)

For any randomized acceptor  $A$  for GNI  $\exists$  polynomial  $p$  such that

$\forall x \in GNI, t_{Opt}(x) \leq p\left(\mu_{y \leftarrow U(C_x)}^{(1/4)}[\tau_A(y)]\right)$ , where

$C_{(G_1, G_2)} = \{(G_1^{\pi_1}, G_2^{\pi_2}) \mid \pi_1, \pi_2 \in S_n\}$  is a *cluster* of  $(G_1, G_2)$ .

# Optimal acceptor for GNI

Algorithm  $Opt(G_1, G_2)$ :

- ▶ Execute in parallel:
  - ▶  $A_1(G_1, G_2)$  (brute-force search),
  - ▶ 3 times  $SelfCorrect_{A_2, 30n}(G_1, G_2)$ ,
  - ▶ 3 times  $SelfCorrect_{A_3, 30n}(G_1, G_2)$ ,
  - ▶ ...
  - ▶ 3 times  $SelfCorrect_{A_n, 30n}(G_1, G_2)$ .
- ▶ Accept if any of the  $3n + 1$  parallel threads accepts.

## Lemma (simulation)

For any randomized acceptor  $A$  for GNI  $\exists$  polynomial  $p$  such that

$\forall x \in GNI, t_{Opt}(x) \leq p\left(\mu_{y \leftarrow U(C_x)}^{(1/4)}[\tau_A(y)]\right)$ , where

$C_{(G_1, G_2)} = \{(G_1^{\pi_1}, G_2^{\pi_2}) \mid \pi_1, \pi_2 \in S_n\}$  is a *cluster* of  $(G_1, G_2)$ .

## Corollary

$Opt$  is average-case optimal provided  $D$  is uniform on every cluster.

## Definition

$L$  is **paddable** if there is an injective non-length-decreasing polynomial-time padding function  $\text{pad}_L: \{0, 1\}^* \times \{0, 1\}^* \rightarrow \{0, 1\}^*$  that is polynomial-time invertible on its image and such that  $\forall x, w (x \in L \iff \text{pad}_L(x, w) \in L)$ .

Optimal proof [Messner, 99]:

- ▶ A proof  $\pi$  of  $x$  in some system  $\Pi$ ;
- ▶ padding.

Verification:

- ▶ run optimal acceptor on  $\text{pad}_L(x, \pi)$ ;
- ▶ for a correct proof  $\pi$ , it accepts in a polynomial time because for a correct system  $\Pi$ , the set  $\{\text{pad}_L(x, \pi) \mid x \in L, \Pi(x, \pi) = 1\} \subseteq L$  can be accepted in a polynomial time.

# From acceptors to proof systems

Optimal proof [Messner, 99]:

- ▶ A proof  $\pi$  of  $x$  in some system  $\Pi$ ;
- ▶ padding.

Verification:

- ▶ run optimal acceptor on  $\text{pad}_L(x, \pi)$ ;
- ▶ for a correct proof  $\pi$ , it accepts in a polynomial time because for a correct system  $\Pi$ , the set  $\{\text{pad}_L(x, \pi) \mid x \in L, \Pi(x, \pi) = 1\} \subseteq L$  can be accepted in a polynomial time.

**Applicability:**

- ▶ Messner's proof goes for randomized algorithms.

# From acceptors to proof systems

Optimal proof [Messner, 99]:

- ▶ A proof  $\pi$  of  $x$  in some system  $\Pi$ ;
- ▶ padding.

Verification:

- ▶ run optimal acceptor on  $\text{pad}_L(x, \pi)$ ;
- ▶ for a correct proof  $\pi$ , it accepts in a polynomial time because for a correct system  $\Pi$ , the set  $\{\text{pad}_L(x, \pi) \mid x \in L, \Pi(x, \pi) = 1\} \subseteq L$  can be accepted in a polynomial time.

**Applicability:**

- ▶ Messner's proof goes for randomized algorithms.
- ▶ Does not go for heuristic, average-case algorithms.

# Open questions

- ▶  $\exists$  optimal proof system  $\iff$   $\exists$  optimal heuristic acceptor;
- ▶  $\exists$  optimal heuristic proof system  $\stackrel{?}{\iff}$   $\exists$  optimal heuristic acceptor;
- ▶  $\exists$  optimal proof system with advice  $\stackrel{?}{\iff}$   $\exists$  optimal acceptor with advice;
- ▶  $\exists$  average-case optimal acceptor?
- ▶  $\exists$  optimal acceptor for GNI or any other  $\mathbf{co-NP} \setminus \mathbf{P}$  problem?
- ▶  $\exists$  optimal proof system for any problem outside  $\mathbf{P}$ ?
- ▶  $\exists (D, L) \in (\mathbf{co-NP}, \text{PSamplable})$  with no polynomially-bounded heuristic proof system  $\iff$  ?
- ▶ **AM** protocols make deterministic (heuristic) proof systems with very small error; suggest another example: randomized and with larger error.

**Deadline:** December 11, 2012

**Date and place:** June 25-29, 2013, Ekaterinburg, Russia

**Program Committee:**

- ▶ Max Alekseyev
- ▶ Andris Ambainis
- ▶ Maxim Babenko
- ▶ Patrick Baillot
- ▶ Glencora Borradaile
- ▶ Andrei Bulatov  
(*Chair*)
- ▶ Yijia Chen
- ▶ Victor Dalmau
- ▶ Yevgeniy Dodis
- ▶ Manfred Droste
- ▶ Anna Frid
- ▶ Hamed Hatami
- ▶ Tero Harju
- ▶ Michal Koucky
- ▶ Stephan Kreutzer
- ▶ Alexander Kulikov
- ▶ Konstantin Makarychev
- ▶ Simone Martini
- ▶ Jaroslav Nesetril
- ▶ Jean-Eric Pin
- ▶ Harald Raecke
- ▶ Alexander Razborov