

# Computing by Observing Insertion

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# Levenshtein Distance

Insertion and deletion are operations of fundamental interest in information theory.

The **Levenshtein Distance** or **Edit Distance** measures the minimum number of

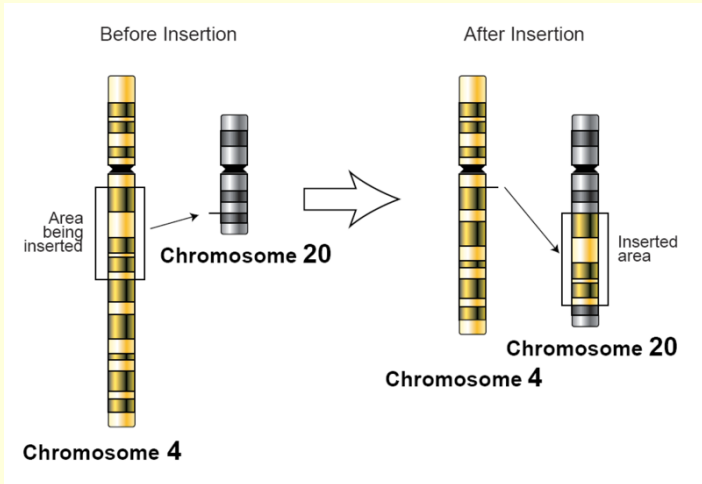
- insertions,
- deletions, and
- substitutions

that are necessary to convert one string into another.

This is motivated from signal transmission, where signals can appear through noise, can be lost, or can be altered.

# DNA Computing

Insertion and deletion as operations on strings have received increased interest in the field of DNA Computing.



Picture from wikipedia.org

## Definition

An **insertion system** is a triple  $(\Sigma, A, R)$ , where

$\Sigma$  is an alphabet,

the set of **axioms**  $A$  is a finite language over  $\Sigma$ , and

the set of **insertion rules**  $R$  is a finite set of triples of the form  $(u, \alpha, v)$ , where  $u$ ,  $\alpha$ , and  $v$  are strings over  $\Sigma$ ,  $\alpha \neq \lambda$ .

# Insertion Rules

The three components of insertion rules are

- left context
- inserted string
- right context

A rule  $[a, bb, ab]$  does the following:

cabaababc

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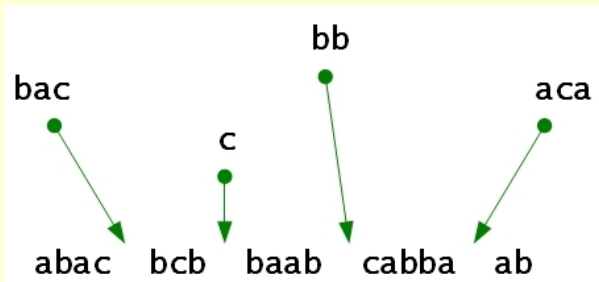
A rule  $[a, bb, ab]$  does the following:

cab**bb**ababc

# Insertion Systems

Every insertion makes the string longer.

So we do not have much computation time for reaching a given string, and neither do we have much control over the place of insertions.





Pure insertion systems have a very limited computational power:

## Theorem

*Every language over the alphabet  $\Sigma$  generated by an insertion system*

- with insertion rules that have empty contexts and*
- insert only one letter*

*is a finite union of languages of the form*

$$X^* x_1 X^* x_2 X^* \dots X^* x_n X^*$$

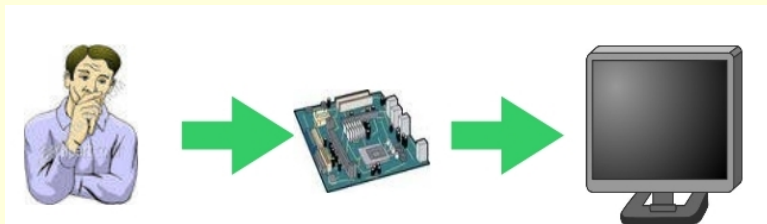
*where for some  $n \geq 0$  we have  $x_1, x_2, \dots, x_n \in \Sigma$  and  $X \subseteq \Sigma$ .*

# Standard DNA Computing

So insertion systems follow the standard approach in DNA Computing:



which is very similar to the standard computer science approach:



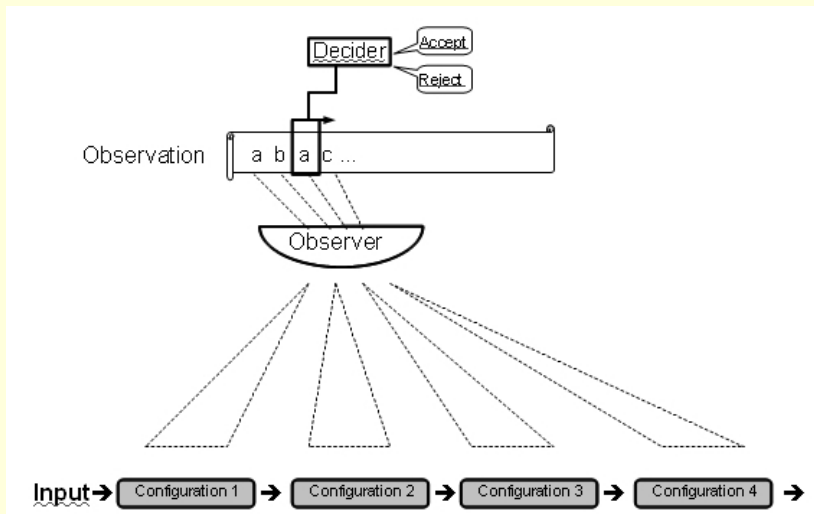
# Computing by Observing

The Computing by Observing architecture is an alternative for DNA computing models that

- does not let the DNA itself produce the output
- but includes an observer that
  - sees the systems configuration in every step and
  - can output one letter per step.

Thus the observer resembles for example a chemist monitoring certain properties (temperature, pH, ...) during an experiment.

# Computing by Observing



## Definition

An **insertion observer system** is a quintuple  $\Omega = [\Delta, R, \mathcal{O}, D, \odot]$ , where

$\mathcal{O}$  is a monadic transducer,

$R$  is an insertion system over the input alphabet  $\Sigma$  of  $\mathcal{O}$ ,

$\Delta$  the system's input alphabet, a subset of  $\Sigma$ , and

$D$  is a regular language over the output alphabet of  $\mathcal{O}$ ;

all words of  $D$  end in the **termination symbol**  $\odot$ .

The observer should

- read the configurations (strings),
- output a symbol and
- be simple.

So we use **Monadic Transducers**, which are basically finite deterministic automata with labels on their states.

## Insertion Observer Systems – Example

- 1 Check, if the input word is from the language  $a^+b^+c^+$ .
- 2 Insert an  $A$  after the first letter  $a$  that is not followed by  $A$ .
- 3 Insert a  $B$  after the first letter  $b$  that is not followed by  $B$ .
- 4 Insert a  $C$  after the first letter  $c$  that is not followed by  $C$ .
- 5 Insert an  $\bar{A}$  after the first letter  $A$  that is not followed by  $\bar{A}$ .
- 6 Insert a  $\bar{B}$  after the first letter  $B$  that is not followed by  $\bar{B}$ .
- 7 Insert a  $\bar{C}$  after the first letter  $C$  that is not followed by  $\bar{C}$ .
- 8 If there is some lower case letter left that is not followed by the corresponding upper case letter: go back to Step (2).
- 9 Accept the input word.

## Insertion Observer Systems – Example

The algorithm accepts the language  $\{a^n b^n c^n : n \geq 0\}$  and is implemented with the insertion rules

$$\{(\lambda, A, \lambda), (\lambda, \bar{A}, \lambda), (\lambda, B, \lambda), (\lambda, \bar{B}, \lambda), (\lambda, C, \lambda), (\lambda, \bar{C}, \lambda)\}.$$

aabbcc

Observation: 1



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aAabbcc

Observation: 2

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aAab**B**bcc

Observation: 3

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aAabBbcCc

Observation: 4

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aA $\bar{A}$ abBbcCc

Observation: 5

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aA $\bar{A}$ abB $\bar{B}$ bcCc

Observation: 6

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aA $\bar{A}$ abB $\bar{B}$ bcC $\bar{C}$ c

Observation: 1

## Insertion Observer Systems – Example

The algorithm accepts the language  $\{a^n b^n c^n : n \geq 0\}$  and is implemented with the insertion rules

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aA $\bar{A}$ aAbB $\bar{B}$ bBcC $\bar{C}$ cC

Observation: 234

## Insertion Observer Systems – Example

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aA $\bar{A}$ aA $\bar{A}$ bB $\bar{B}$ bB $\bar{B}$ cC $\bar{C}$ cC $\bar{C}$

Observation: 56⊙



# Insertion Observer Systems – Example

The observer mapping is:

$$\mathcal{O}(w) = \begin{cases} 1 & \text{if } w \in (aA\bar{A})^* a^+ (bB\bar{B})^* b^+ (cC\bar{C})^* c^+, \\ 2 & \text{if } w \in (aA\bar{A})^* aAa^* (bB\bar{B})^* b^+ (cC\bar{C})^* c^+, \\ 3 & \text{if } w \in (aA\bar{A})^* aAa^* (bB\bar{B})^* bBb^* (cC\bar{C})^* c^+, \\ 4 & \text{if } w \in (aA\bar{A})^* aAa^* (bB\bar{B})^* bBb^* (cC\bar{C})^* cCc^*, \\ 5 & \text{if } w \in (aA\bar{A})^+ a^* (bB\bar{B})^* bBb^* (cC\bar{C})^* cCc^*, \\ 6 & \text{if } w \in (aA\bar{A})^+ a^* (bB\bar{B})^+ b^* (cC\bar{C})^* cCc^*, \\ \odot & \text{if } w \in (aA\bar{A})^+ (bB\bar{B})^+ (cC\bar{C})^+, \\ \perp & \text{else.} \end{cases}$$

The decider accepts the language  $(123456)^+ \odot$ .

# Insertion Observer Systems

The key techniques used in this example are:

- Using complementation instead of deletion.
- Use phases of marking for coordination.

In this way, we can simulate rewritability:

Instead of  $a \rightarrow a' \rightarrow a''$  we use  $a \rightarrow aA \rightarrow aA\bar{A}$ .

And we can simulate context-sensitivity:

Instead of  $ab \rightarrow AB$  we use  $ab \rightarrow aAb \rightarrow aAbB \rightarrow a\bar{a}AbB \rightarrow a\bar{a}Ab\bar{b}B$ .

Using the techniques used in the example, we can actually simulate a Turing Machine.

## Theorem

*Every recursively enumerable language can be accepted by an insertion observer system*

- *with insertion rules that have empty contexts and*
- *insert only one letter.*

# Insertion Observer Systems

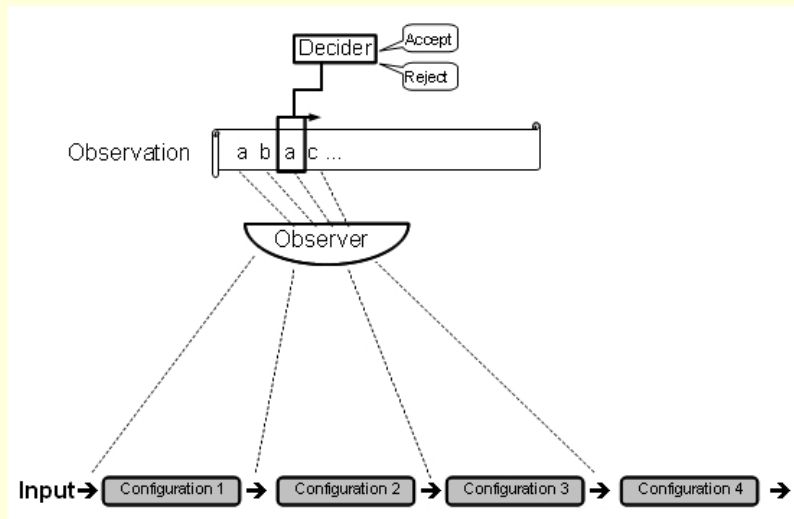
So with sub-regular insertion systems and regular observers we achieve computational completeness.

NICE: our architecture provides us with power far beyond the components' power.

NOT SO NICE: we obtain completeness very quickly.

Therefore we consider variants with less powerful modes of observation.

# Observing Change



## Observing Change – Example

We can accept  $\{a^n b^n c^n : n \geq 0\}$  as the following three conditions characterize exactly the words from this language:

- 1 There is exactly one occurrence of each  $ab$  and  $bc$ .
- 2 The numbers of  $aa$ ,  $bb$  and  $cc$  are equal.
- 3 Other blocks of two letters ( $ac$ ,  $ba$ ,  $ca$ ,  $cb$ ) do not occur.

We use insertion rules  $(x, \Delta, y)$  for all pairs of letters  $x$  and  $y$ .

# Observing Change

Restricting to the observation of change restricts computational power:

## Theorem

*The singleton language  $\{a^2ba\}$  cannot be accepted by any insertion change-observing acceptor*

- *with insertion rules that have left and right contexts of length at most one each and*
- *insert an arbitrary number of letters.*

The strings  $a^2ba$  and  $aba^2$  generate exactly the same sequences of rule applications.

# Observing Change

The lack of control over the place of insertion could be compensated by more context.

## Conjecture

Insertion change-observing acceptors

- with insertion rules that have left and right contexts of length two each and
- insert strings of length two

can accept all recursively enumerable languages.