

Compositional Abstraction Techniques for Probabilistic Automata (PA)

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RWTH Aachen

September 26, 2012

Contents

1 Motivation

- What is an abstraction?
- How to analyse an abstract system?

2 Probabilistic Automata (PA)

- Abstraction with modal PA (MPA)
- Abstraction with abstract PA (APA)

3 Abstract Probabilistic Automata (APA)

- Reachability analysis of APA
- Abstraction and Refinement

4 Conclusion and Future work

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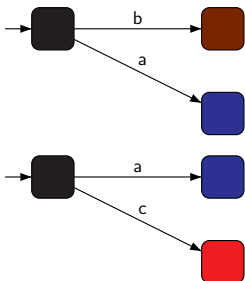
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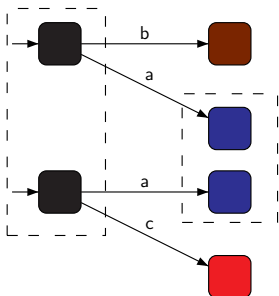
Abstraction of Labelled TS (LTS) with Modal TS (MTS)

LTS



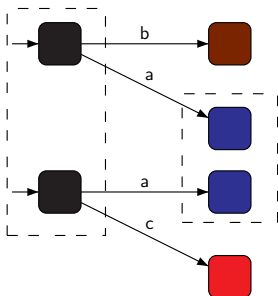
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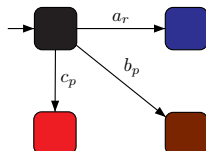


Abstraction of Labelled TS (LTS) with Modal TS (MTS)

LTS



MTS



Modal Transition Systems: A Foundation for Three-Valued Program Analysis
 by Michael Huth, Radha Jagadeesan and David Schmidt. In: LNCS, Vol 2028.
 Springer (2001).

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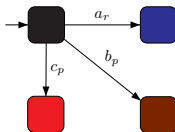
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- Abstraction and Refinement

4 Conclusion and Future work

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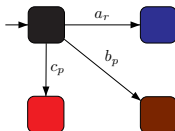
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MTS

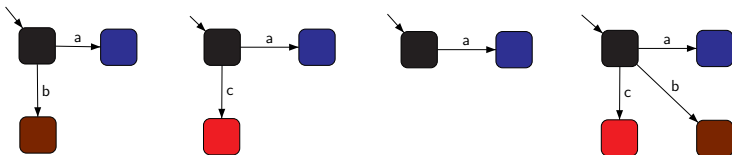
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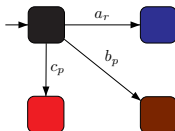
MTS

- Is it possible to reach a **red state** in each implementation of N ?



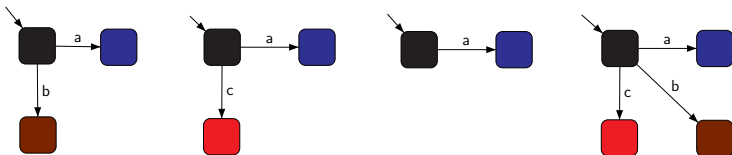
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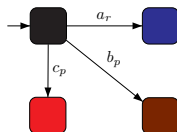
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- **Don't know!!!**

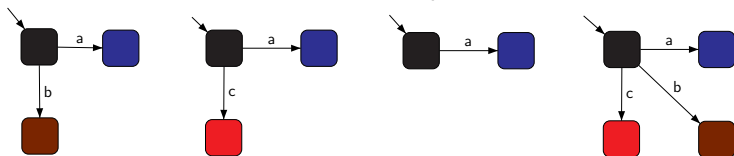
Analysis of a modal TS (MTS)

- Is it possible to reach a **red state** in N ?



MTS

- Is it possible to reach a **red state** in each implementation of N ?



- Don't know!!!**

- Is it possible to reach a **blue state** in N ? **Yes we can!!!**

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- 1 Motivation
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Probabilistic automata (PA)

Definition

A PA is a tuple $N = (S, A, \Delta, s_0)$

where:

- S is a set of states, with $s_0 \in S$
- A is a set of actions, and
- $\Delta \subseteq S \times A \times \text{Dist}(S)$ is a set of transitions.

where $\text{Dist}(S)$ is a set of distributions over S .

Probabilistic automata (PA)

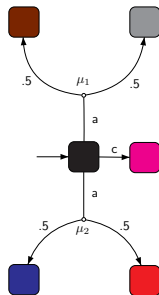
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PA M_1



Modeling and Verification of Randomized Distributed Real-Time Systems by Roberto Segala (1995).

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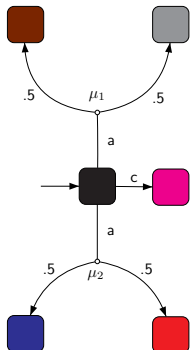
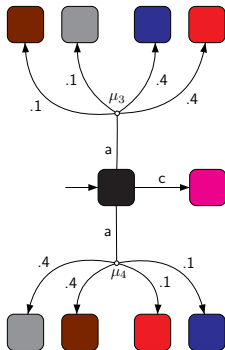
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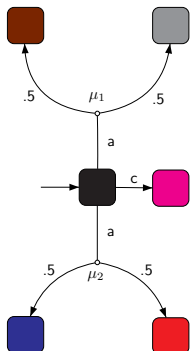
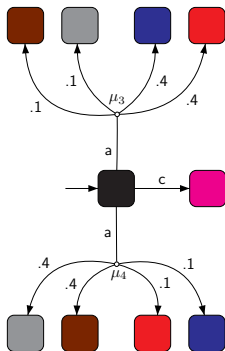
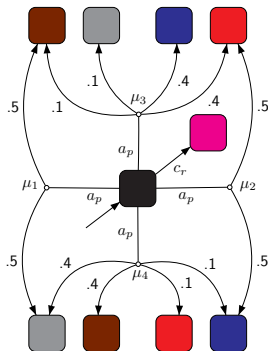
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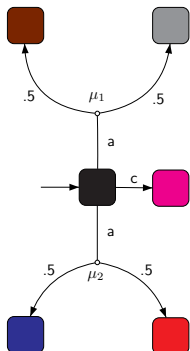
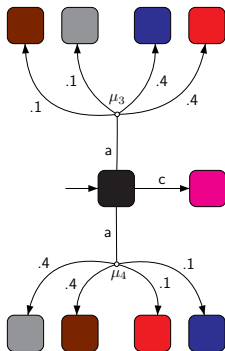
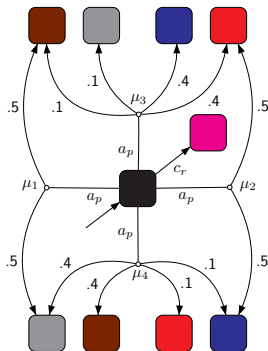
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PA M_1 PA M_2

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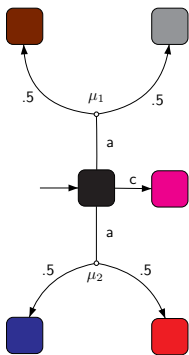
PA M_1 PA M_2 Modal PA N

Is it possible to reach a **blue state** with probability $\geq .1$? **Don't know!!!**

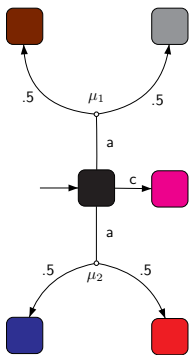
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- 2 Probabilistic Automata (PA)
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Simplification of PA

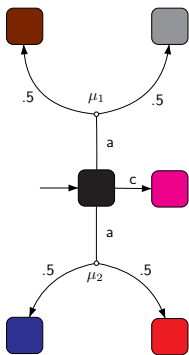
PA M_1

Simplification of PA

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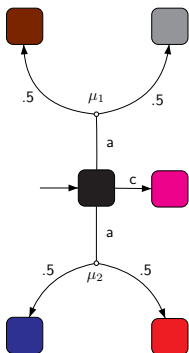
- Represent all combined a -transitions by one a -transition.

Simplification of PA

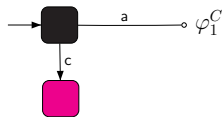
PA M_1

- Represent all combined a -transitions by one a -transition.
- let $\varphi_1 = \{\mu_1, \mu_2\}$ and $\varphi_1^C = \{c_1 \cdot \mu_1 \oplus c_2 \cdot \mu_2 \mid c_1 + c_2 = 1\}$

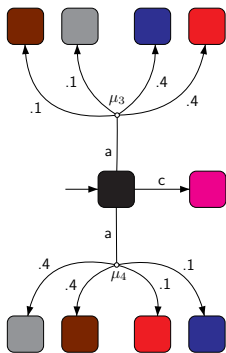
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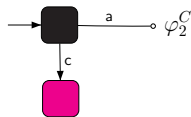
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Constrained PA (CPA) N_1

Simplification of PA

PA M_2

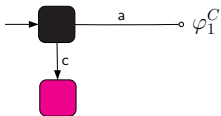
- Represent all combined a -transitions by one a -transition.
- let $\varphi_2 = \{\mu_3, \mu_4\}$ and $\varphi_2^C = \{c_3 \cdot \mu_3 \oplus c_4 \cdot \mu_4 \mid c_3 + c_4 = 1\}$

Constrained PA (CPA) N_2

Abstraction of PA with abstract PA (APA)

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- $\mu_1 = \llbracket .5 \blacksquare, .5 \blacksquare \rrbracket$
- $\mu_2 = \llbracket .5 \blacksquare, .5 \blacksquare \rrbracket$
- $\varphi_1 = \{\mu_1, \mu_2\}$
- $\varphi_1^C = \{c_1 \cdot \mu_1 \oplus c_2 \cdot \mu_2 \mid c_1 + c_2 = 1\}$

CPA N_1

Abstraction of PA with abstract PA (APA)

$$\blacksquare \mu_1 = \llbracket .5 \blacksquare, .5 \blacksquare \rrbracket$$

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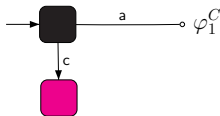
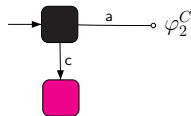
$$\blacksquare \varphi_1^C = \{c_1 \cdot \mu_1 \oplus c_2 \cdot \mu_2 \mid c_1 + c_2 = 1\}$$

$$\blacksquare \mu_3 = \llbracket .1 \blacksquare, .1 \blacksquare, .4 \blacksquare, .4 \blacksquare \rrbracket = .2\mu_1 \oplus .8\mu_2$$

$$\blacksquare \mu_4 = \llbracket .4 \blacksquare, .4 \blacksquare, .1 \blacksquare, .1 \blacksquare \rrbracket = .8\mu_1 \oplus .2\mu_2$$

$$\blacksquare \varphi_2 = \{\mu_3, \mu_4\}$$

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CPA N_1 CPA N_2

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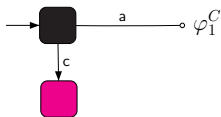
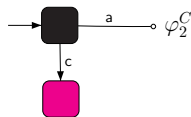
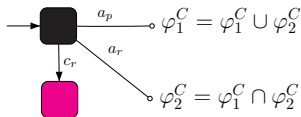
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CPA N_1 CPA N_2 APA N

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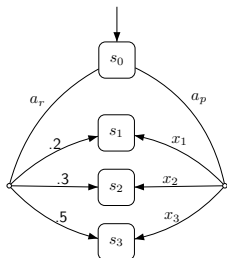
- $\Delta_r \subseteq S \times A \times C(S)$ is a set of *required* transitions,
 - $\Delta_p \subseteq S \times A \times C(S)$ is a set of *possible* transitions with $\Delta_r \subseteq \Delta_p$,
- $C(S)$ is a set of polynomial constraints.

Abstract Probabilistic Automata (APA)

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- $C(S)$ is a set of polynomial constraints.



$$\varphi_x = (x_1 = .4 \wedge x_2 = .6) \vee x_3 = 1$$

An APA



Abstract Probabilistic Automata by Benoît Delahaye, Joost-Pieter Katoen, Kim G. Larsen, Axel Legay, Mikkel L. Pedersen, Falak Sher and Andrzej Wasowski. In VMCAI . LNCS, Vol 6538. Springer (2011).

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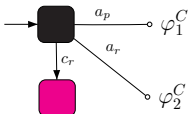
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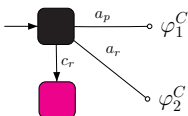
Probabilistic reachability in APA

- Is it possible to reach a **blue state** with probability $\geq .1$ in N ?



Probabilistic reachability in APA

- Is it possible to reach a **blue state** with probability $\geq .1$ in N ?



- Is it possible to reach a **blue state** with probability $\geq .1$ in each implementation of N ?

Challenges in the analysis of APA

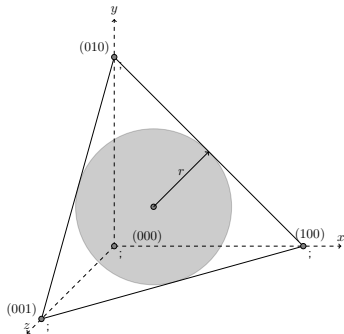
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- **Challenge:** Infinite implementations are possible because of polynomial constraint functions.

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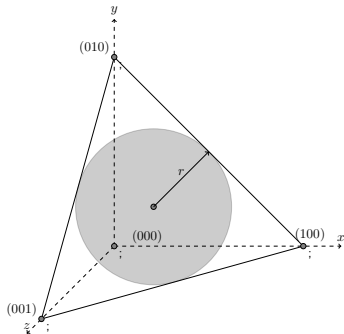
$$\varphi = (x^2 + y^2 + z^2 \leq r^2 \wedge x + y + z = 1)$$



Challenges in the analysis of APA

- **Challenge:** Infinite implementations are possible because of polynomial constraint functions.

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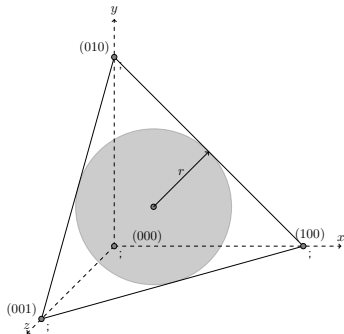


- **Two step solution:**
 - **Step 1:** Approximate polynomial constraints by linear ones.

Challenges in the analysis of APA

- **Challenge:** Infinite implementations are possible because of polynomial constraint functions.

$$\varphi = (x^2 + y^2 + z^2 \leq r^2 \wedge x + y + z = 1)$$



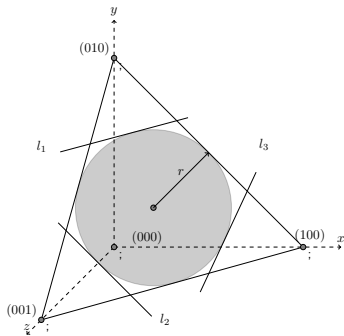
- **Two step solution:**

- **Step 1:** Approximate polynomial constraints by linear ones.
- **Step 2:** Exploit extreme distributions of linear constraints.

Solution: (1) Approximation of a polynomial constraint function by a linear one

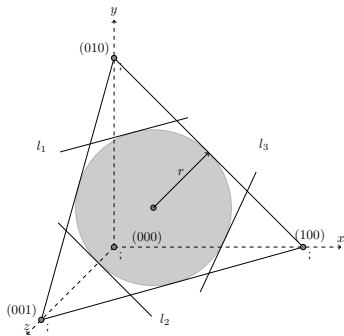
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Over-approximation



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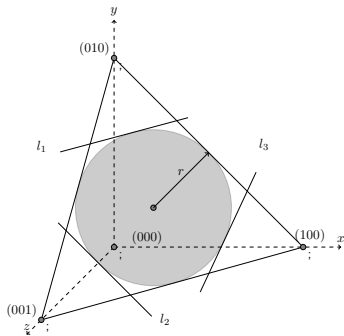
Over-approximation



■ $\varphi' = \{\mu \mid \mu \text{ is enclosed by } l_1 \text{ to } l_3\}$

Solution: (1) Approximation of a polynomial constraint function by a linear one

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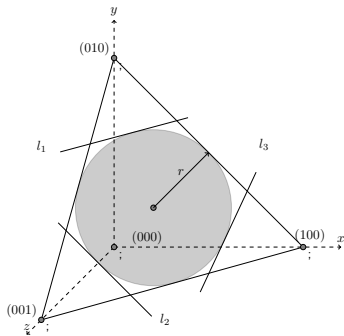


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- $\varphi \subseteq \varphi'$

Solution: (1) Approximation of a polynomial constraint function by a linear one

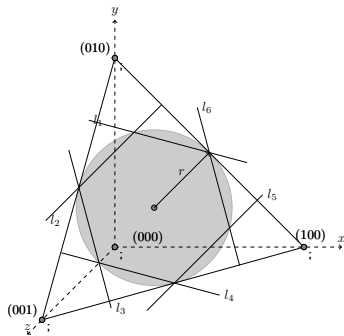
Over-approximation



■ $\varphi' = \{\mu \mid \mu \text{ is enclosed by } l_1 \text{ to } l_3\}$

■ $\varphi \subseteq \varphi'$

Under-approximation



■ $\varphi' = \{\mu \mid \mu \text{ is enclosed by } l_1 \text{ to } l_6\}$

■ $\varphi \supseteq \varphi'$

Solution: (1) Effect of constraint-approximation on APA

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Let N be an APA, then for every state s :

- if $s \xrightarrow{a}_r \varphi$, then under-approximate φ .

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then for the resultant APA N' :

Solution: (1) Effect of constraint-approximation on APA

Let N be an APA, then for every state s :

- if $s \xrightarrow{a}_r \varphi$, then under-approximate φ .
- if $s \xrightarrow{a}_p \varphi$, then over-approximate φ .

then for the resultant APA N' :

- if PA M is an implementation of N , its also an implementation of N' .

Solution: (2) Exploitation of extreme distributions of linear constraints

■ Two step solution:

- **Step 1:** Approximate polynomial constraints by linear ones. **Done**
- **Step 2:** Exploit extreme distributions of linear constraints.

Solution: (2) Exploitation of extreme distributions of linear constraints

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- **Step 1:** Approximate polynomial constraints by linear ones. **Done**
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- **Extreme distributions** of a linear constraint φ are the distributions of the smallest $\varphi_{extr} \subseteq \varphi$ such that $\varphi_{extr}^C = \varphi^C$.

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■ Two step solution:

- **Step 1:** Approximate polynomial constraints by linear ones. **Done**
- **Step 2:** Exploit extreme distributions of linear constraints.

- **Extreme distributions** of a linear constraint φ are the distributions of the smallest $\varphi_{extr} \subseteq \varphi$ such that $\varphi_{extr}^C = \varphi^C$.
- Let $\varphi = \{\eta_1, \eta_2, .2 \cdot \eta_1 \oplus .8 \cdot \eta_2\}$, then $\varphi_{extr} = \{\eta_1, \eta_2\}$.

Solution: (2) Exploitation of extreme distributions of linear constraints

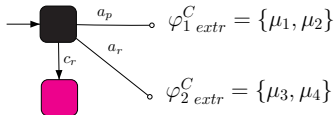
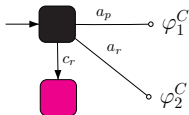
■ Two step solution:

- **Step 1:** Approximate polynomial constraints by linear ones. **Done**
- **Step 2:** Exploit extreme distributions of linear constraints.

■ **Extreme distributions** of a linear constraint φ are the distributions of the smallest $\varphi_{extr} \subseteq \varphi$ such that $\varphi_{extr}^C = \varphi^C$.

■ Let $\varphi = \{\eta_1, \eta_2, .2 \cdot \eta_1 \oplus .8 \cdot \eta_2\}$, then $\varphi_{extr} = \{\eta_1, \eta_2\}$.

■ For our running example:

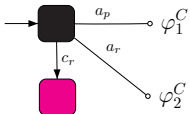


$$\varphi_1^C = \{c_1 \cdot \mu_1 \oplus c_2 \cdot \mu_2 \mid c_1 + c_2 = 1\}$$

$$\varphi_2^C = \{c_3 \cdot \mu_3 \oplus c_4 \cdot \mu_4 \mid c_3 + c_4 = 1\}$$

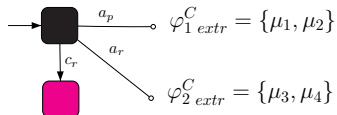
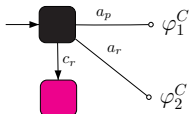
Probabilistic reachability in APA

- Is it possible to reach a blue state with probability $\geq .1$ in N ?



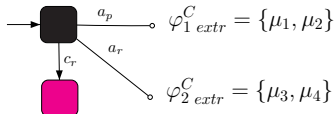
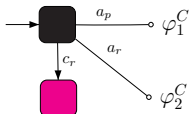
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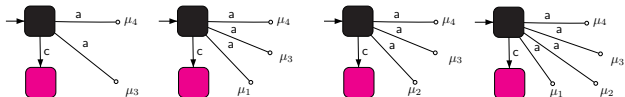


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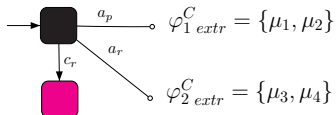
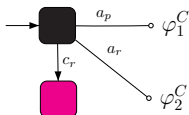


- Get all possible implementations of simplified APA:

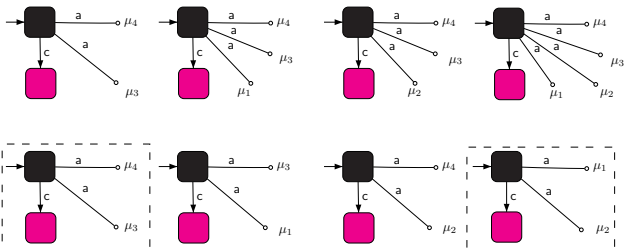


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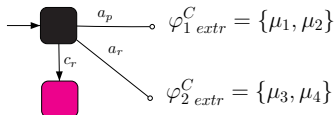
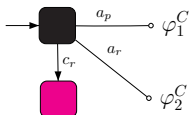


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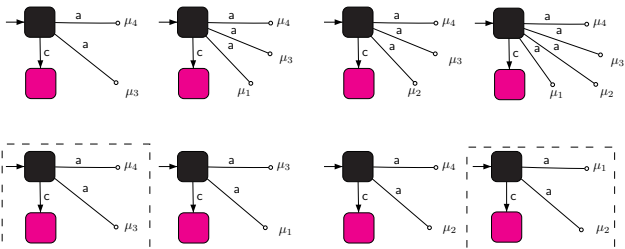


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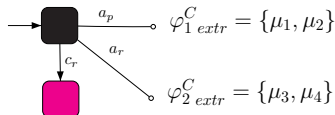
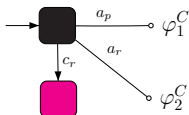
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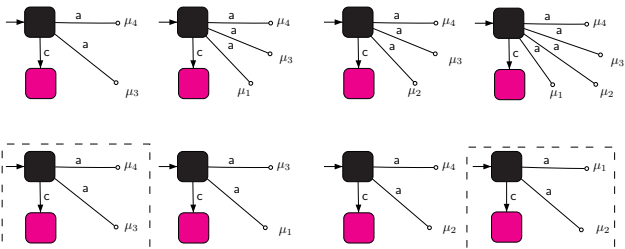
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Probabilistic reachability in APA

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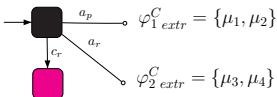
- $\mu_4(\blacksquare) = 0.1$ and $\blacksquare \xrightarrow{a} \mu_4$ is present in each implementation.

- Yes, its possible!!!**

Lower/upper bounds of maximum reachability probabilities and extreme implementations of APA

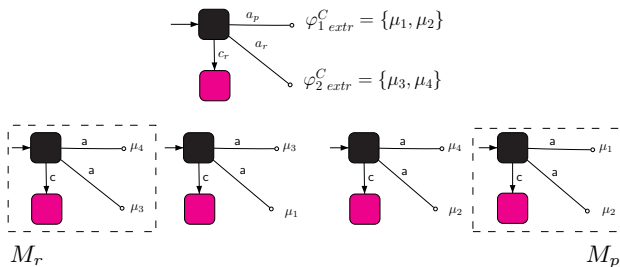
Lower/upper bounds of maximum reachability probabilities and extreme implementations of APA

- Is the maximum probability to reach a **blue state** between .4 and .5 in N ?



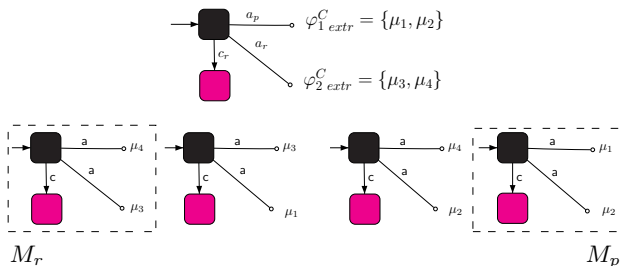
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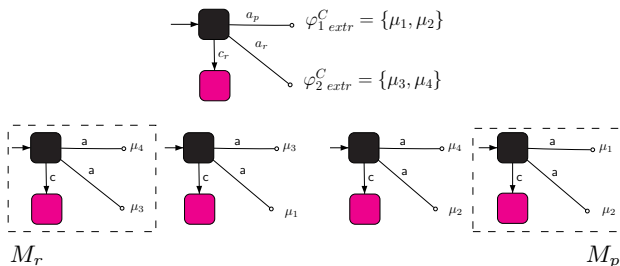
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- Analysis of extreme implementations of APA N answers the above question.

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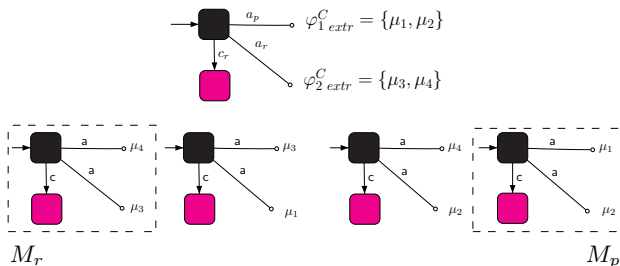
- Is the maximum probability to reach a **blue state** between .4 and .5 in N ?



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- $\mu_1 = [.5 \blacksquare, .5 \blacksquare]$, $\mu_2 = [.5 \blacksquare, .5 \blacksquare]$,
- $\mu_3 = [.1 \blacksquare, .1 \blacksquare, .4 \blacksquare, .4 \blacksquare]$, $\mu_4 = [.4 \blacksquare, .4 \blacksquare, .1 \blacksquare, .1 \blacksquare]$

Lower/upper bounds of maximum reachability probabilities and extreme implementations of APA

- Is the maximum probability to reach a **blue state** between .4 and .5 in N ?



- Analysis of extreme implementations of APA N answers the above question.
- $\mu_1 = \llbracket .5 \blacksquare, .5 \blacksquare \rrbracket$, $\mu_2 = \llbracket .5 \blacksquare, .5 \blacksquare \rrbracket$,
- $\mu_3 = \llbracket .1 \blacksquare, .1 \blacksquare, .4 \blacksquare, .4 \blacksquare \rrbracket$, $\mu_4 = \llbracket .4 \blacksquare, .4 \blacksquare, .1 \blacksquare, .1 \blacksquare \rrbracket$
- Yes:** $\mu_3(\blacksquare) = .4$ and $\mu_2(\blacksquare) = .5$

Theorems

Theorem

Let M_r and M_p be the extreme implementations of APA N , then for a set G of goal states:

$$Pr_{max}(M_r, G) \leq Pr_{max}(N, G) \leq Pr_{max}(M_p, G)$$

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- **Abstraction and Refinement**

4 Conclusion and Future work

Abstraction of APA

Abstraction of APA

Definition

(Multi-transition (\mapsto))

$s \mapsto_p \varphi'$ iff $s \xrightarrow{a}_p \varphi_1, s \xrightarrow{a}_p \varphi_2, \dots, s \xrightarrow{a}_p \varphi_n$ and $\varphi' = \bigvee_{i=1}^n \varphi_i$.

Abstraction of APA

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Definition

(Abstraction) For APA N , the abstraction function $\alpha : S \rightarrow S'$ induces the APA $N' = \alpha(N)$ where for all $s' \in S'$:

- 1 $s' \xrightarrow{a}_r \varphi' \quad \text{iff} \quad \forall s \in \alpha^{-1}(s'): s \xrightarrow{a}_r \varphi \quad \text{and} \quad \varphi' = \bigwedge_{u \in \alpha^{-1}(s'): u \xrightarrow{a}_r \varphi} \alpha(\varphi)^C,$
- 2 $s' \xrightarrow{a}_p \varphi' \quad \text{iff} \quad \exists s \in \alpha^{-1}(s'): s \xrightarrow{a}_p \varphi \quad \text{and} \quad \varphi' = \bigvee_{u \in \alpha^{-1}(s'): u \xrightarrow{a}_p \varphi} \alpha(\varphi)$

Abstraction of APA

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Theorem

$$\alpha_1(N_1) \parallel_{\bar{A}} \alpha_2(N_2) = (\alpha_1 \times \alpha_2)(N_1 \parallel_{\bar{A}} N_2)$$

Refinement of APA

Refinement of APA

Definition

(Refinement (\preceq)) For APA N and N' , a relation $R \subseteq S \times S'$ is a *refinement* relation if for every sRs' :

- 1 $s' \xrightarrow{a}_r \varphi'$ implies $s \xrightarrow{a}_r \varphi$ and $\forall \mu' \in \varphi', \exists \mu \in \varphi^C : \mu R \mu'$.
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Theorem

For APA N , $N \preceq \alpha(N)$.

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Conclusion

Following are the contributions of my work for APA:

- a novel **compositional abstraction technique** that helps defining **lower/upper** bounds for **maximum** reachability probabilities,
- probabilistic reachability analysis of PA.
- a new notion of a **refinement relation** that is pre-congruence w.r.t parallel composition,

Future work

Future work includes:

- design and implementation of algorithms for abstract-refinement framework for APA.
- lifting the notion of abstraction/refinement from states to distributions.

Thanks